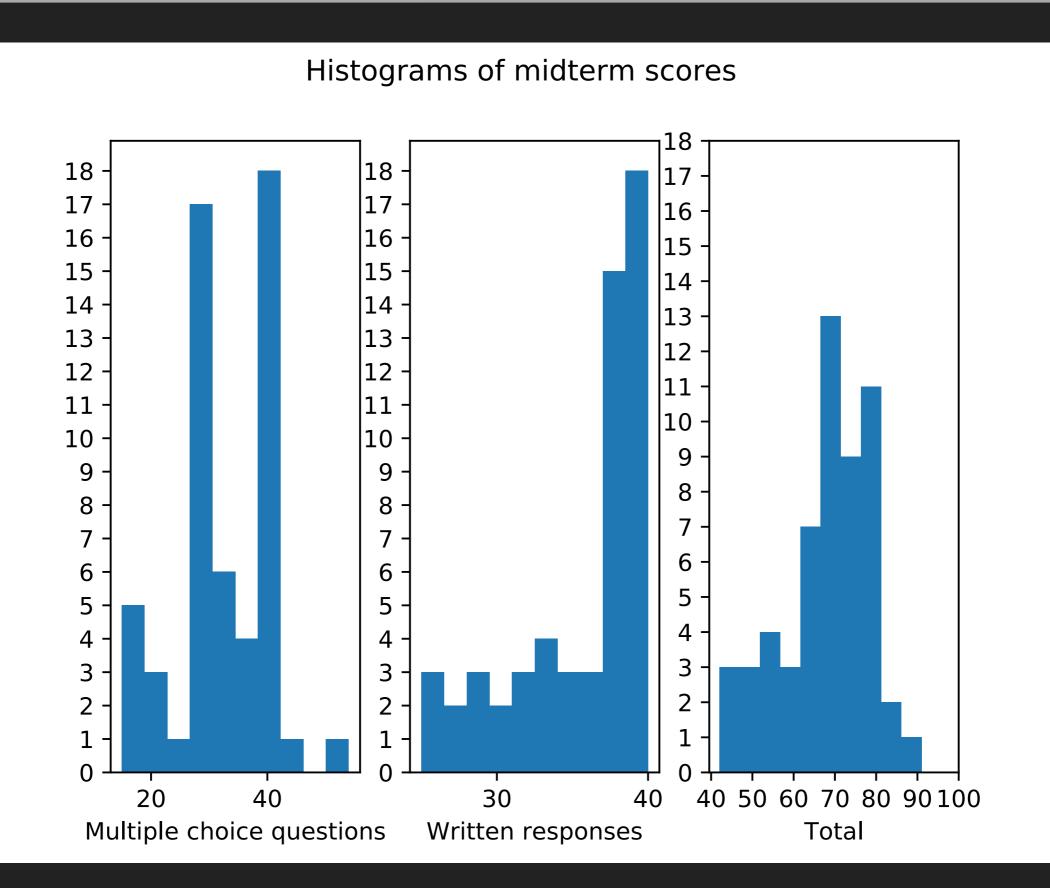
### CSCI 5922 - NEURAL NETWORKS AND DEEP LEARNING

# DEEP LEARNING SOFTWARE

**MIDTERM** 



#### HISTORY OF FRAMEWORKS

FIRST GEN	define-b	neworks to y-run auton iation.		ENERATION
			Framework	Year
Framework	Year		Autograd	2015
Torch	2002		Chainer	2015
Theano	2010	-	MXNet	2015
Torch7	2011		TensorFlow	2016
Theano	2012		Theano	2016
Pylearn2	<u>\ 2013</u>		DyNet	2017
	<u>\ 2015</u>		PyTorch	2017
<b>Torchnet</b>	<u>\</u> 2015		Ignite	2018
			TensorFlow	

Wrappers

First full frameworks to support CUDA/GPUs.

While this version of Torch pre-dates deep learning, it is the prototype for contemporary machine learning frameworks. Most contemporary deep learning frameworks, consciously or not, mimic Torch.

Torch is written in C++ and supports machine learning algorithms like multi-layer neural networks, support vector machines, Gaussian mixture models, and hidden Markov models.

It was made available under the BSD license (free to copy and commercial use/proprietary modifications are allowed as long as attribution is preserved).

The core API is inspired by object-oriented programming and design patterns – specifically, by the notions of modularity and separation of interface and implementation. The API contains useful abstractions like:

- DataSet
- Machine
- Measurer
- Trainer

#### DATASET CLASS

- Responsible for loading data
- Relieves engineer of need to repeatedly write code to read training data and labels
- Provides an abstraction layer that allows data to be read from any source
- Design pattern: Proxy

#### **MACHINE CLASS**

- Responsible for learning mapping from inputs to targets
- Several learning algorithms supported
  - Multi-layer neural network
  - Support vector machine
  - "Distribution"
    - Gaussian mixture model
    - Hidden Markov model
- Design pattern: Adapter

#### **MEASURER CLASS**

- Responsible for measuring the output of the machine
  - Loss: mean squared error, log loss
  - Metric: accuracy, F1, etc.
- Design pattern: ?

#### **TRAINER CLASS**

- Responsible for optimizing the Machine
  - Stochastic gradient trainer (multi-layer neural network)
  - Quadratic constrained trainer (support vector machine)
- Also responsible for ensembling
  - To train with/as an ensemble, an ordinary trainer is a delegate of a bagging or boosting trainer, e.g. (pseudocode):
    - BaggingTrainer(QuadraticConstrainedTrainer(...))
    - BoostingTrainer(StochasticGradientTrainer(...))
- Design pattern: Controller

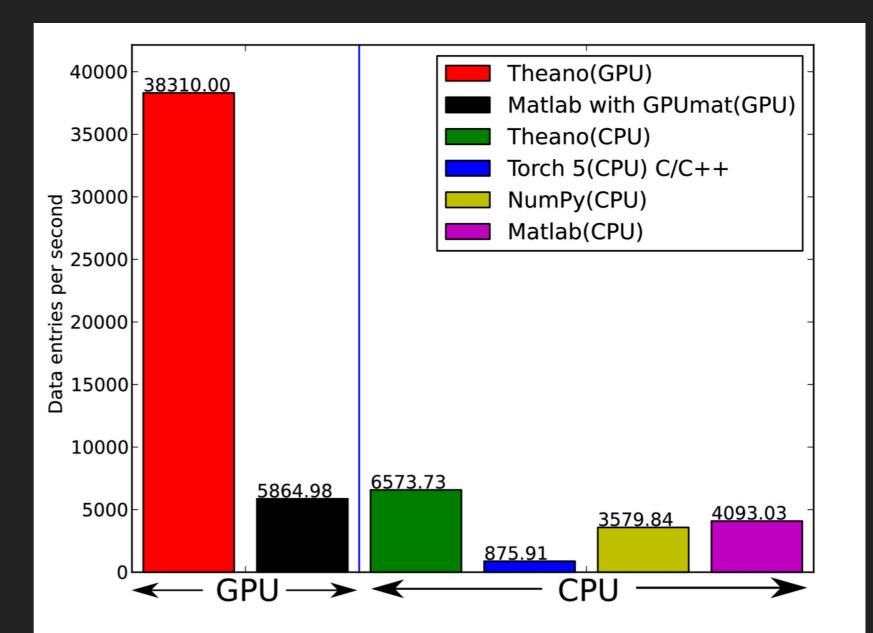
- Large-scale deep unsupervised learning using graphics processors, Raina, Madhavan, and Ng, 2009 [PDF]
- Deep Big Simple Neural Nets Excel on Handwritten Digit <u>Recognition</u>, Ciresan, Meier, Gambardella, and Schmidhuber, 2010 [arXiv]
- ImageNet Classification with Deep Convolutional Neural Networks, Krizhevsky, Sutskever, and Hinton, 2012

#### ENTER GRAPHICS PROCESSING UNITS

The computational workhorse of multi-layer neural networks is matrix multiplication, which has complexity O(n^3).

Matrix multiplication can be seen a set of dot products between rows of the left operand and the columns of the right operand matrix. Naively, each dot product can be dispatched to a different core on a GPU.

With cores numbering in the thousands, GPUs can run many operations on matrices faster than CPUs can, even with slower clock cycles.



Multi-Layer Perceptron: 60x784 matrix times 784x500 matrix, tanh, times 500x10 matrix, elemwise, then all in reverse for backpropagation.

- Mathematical symbolic expression compiler
- Written in Python better than C++ for rapid prototyping
- Attempts to conform to NumPy syntax and semantics
- With transparent support for GPUs

```
import numpy as np
import theano
import theano.tensor as T
# Define the symbolic expression
x = T.scalar('x')
```

```
y = T.scalar('y')
```

```
z = x + y
```

# Define the function inputs and outputs. Calling this
# function causes C source code to be generated and compiled,
# either for the CPU or GPU, depending on your configuration.
f = theano.function(inputs=[x, y], outputs=z)

```
# Then call the function, which returns a numpy array.
results = f(1, 10)
```

```
# Now run it from the command line.
$ THEANO_FLAGS='device=cpu' python theano_example_1.py
11.0
```

LINEAR

**REGRESSION IN** 

TWO SLIDES.

```
from collections import OrderedDict
from sklearn.datasets import make regression
import numpy as np
import theano
import theano.tensor as T
# Define the symblic expression, including the model parameters.
w = \text{theano.shared}(0., \text{name}='w')
b = theano.shared(0., name='b')
x = T.vector('x')
y = T.scalar('y')
output = w^*x + b
# Define the scalar cost and state what gradients to compute.
cost = ((output - y) * * 2).mean()
qw, qb = T.grad(cost, [w, b])
# Define the updates.
updates = OrderedDict()
updates [w] = w-0.1 \star qw
updates[b] = b-0.1*qb
# Define the function inputs and outputs.
```

```
f = theano.function(inputs=[x, y], outputs=output, updates=updates)
```



```
# Now make a regression dataset with a known coefficient and bias.
bias=66.
n_samples=20
X, y, coef = make_regression(
    n_samples=n_samples, n_features=1, coef=True, bias=bias)
# Then iterate over the training examples. The updates are automatically applied.
for i in range(len(X)):
    results = f(X[i], y[i])
print('True coefficient {:.03f} bias {:.03f}'.format(coef, bias))
print('Estimated coefficient {:.03f} bias {:.03f}'.format(w.get_value(), b.get_value()))
```

```
# Now run it from the command line.
$ THEANO_FLAGS='device=cpu,floatX=float64' python theano_example_2.py
True coefficient 82.199 bias 66.000
Estimated coefficient 83.316 bias 66.895
```

#### THEANO - 2011 - <u>HTTP://WWW.DEEPLEARNING.NET/SOFTWARE/THEANO/</u>

```
import numpy as np
                                                      COMPUTING ELEMENT-WISE POWERS
  M = np.random.normal(size=(10, 5))
  result = M.copy()
                                                            OF A MATRIX IN NUMPY
  k = 10
  for i in range(k):
      result = result * M
                  import theano
COMPUTING
                   import theano.tensor as T
THE SAME IN
                → k = T.iscalar('k')
                  A = T.vector('A')
 THEANO
                   # Symbolic description of the result
                   result, updates = theano.scan(
                       fn=lambda prior result, A: prior result * A,
                       outputs info=T.ones like(A),
                      non sequences=A,
                       n steps=k)
                  # We only care about A**k, but scan has provided us with A**1 through
                   # A**k. Discard the values that we don't care about. Scan is smart enough
                   # to notice this and not waste memory saving them.
                  final result = result[-1]
                   # Compiled function that returns A**k
                  power = theano.function(inputs=[A,k], outputs=final result, updates=updates)
                   results = power(range(10), 2)
```

#### SOME LIMITATIONS OF THEANO

- Poor expressivity
  - Example: theano.scan
- Corollary: Not a true automatic differentiation framework
- Because of compilation step (either to CPU or GPU), there can be a substantial delay between program invocation and execution. The delays for recurrent networks could be substantial.
- No longer being actively developed, because of success of other frameworks

- Torch7 was a continuation of the earlier versions of Torch, with nice, modular design.
- GPU support easy to move tensors to and from GPU
- Define-then-run, but not symbolic
- Written in Lua (!)
- Rationale for Lua was ease of extensibility (in C++)
- Super fast

#### **TOP-LEVEL PACKAGES**

- torch numerical library
- nn neural networks
- optim optimization
- image image loading, preprocessing, and manipulation
- paths filesystem-related functions

THE NOTION OF Containers in E.G. Keras Originated in Torch.

A CONTAINER IS AN INSTANCE OF THE MODULE CLASS, AND INSTANCES OF MODULE ARE ADDED TO THE CONTAINER.

> A CONTAINER CAN BE ADDED TO ANOTHER CONTAINER.

```
require 'nn';
```

```
model = nn.Sequential()
```

```
# First convolution.
model:add(nn.SpatialConvolutionMM(1, 32, 5, 5))
model:add(nn.Tanh())
model:add(nn.SpatialMaxPooling(2, 2, 2, 2))
```

```
# Second convolution.
model:add(nn.SpatialConvolutionMM(32, 64, 5, 5))
model:add(nn.Tanh())
model:add(nn.SpatialMaxPooling(2, 2, 2, 2))
```

```
# Fully-connected layers.
model:add(nn.Reshape(64 * 4 * 4))
model:add(nn.Linear(64 * 4 * 4, 200))
model:add(nn.Tanh())
model:add(nn.Linear(200, 10))
```

#### TORCHNET - 2015



require 'nn' require 'torchnet' require 'cunn'

```
local net = nn.Sequential():add(nn.Linear(784,10))
local criterion = nn.CrossEntropyCriterion()
```

```
-- Put network and loss function on GPU.
net = net:cuda()
criterion = criterion:cuda()
```

-- CudaTensor is put on GPU by default. local input = torch.CudaTensor() local target = torch.CudaTensor()

local engine = torchnet.SGDEngine()

#### ENGINE IN TORCHNET SIMILAR TO TRAINER IN 2002 TORCH.

```
HOOKS ALLOW USER TO
RUN CODE AT CERTAIN
POINTS IN EXECUTION.
```

#### \_\_[

Each time the engine receives a new sample from the dataset iterator, resize the input and target tensors to match the sizes in the minibatch, and copy from the CPU to the GPU.

```
]]--
```

engine.hooks.onSample = function(state)
input:resize(

```
state.sample.input:size()
):copy(state.sample.input)
```

```
target:resize(
```

```
state.sample.target:size()
):copy(state.sample.target)
```

```
state.sample.input = input
state.sample.target = target
end
```

#### SOME LIMITATIONS OF TORCH7



# (particularly for NLP tasks, but even for vision)

## PYLEARN2 WAS A WRAPPER FOR THEANO. IT WAS WRITTEN AT THE UNIVERSITY OF MONTREAL IN THE SAME LAB THAT CREATED THEANO.

```
!obj:pylearn2.train.Train {
                     "dataset": !obj:pylearn2.datasets.dense design matrix.DenseDesignMatrix &dataset {
                       "X" : !obj:numpy.random.normal { 'size':[5,3] },
                     },
  A YAML FILE
                     "model": !obj:pylearn2.models.autoencoder.DenoisingAutoencoder {
                       "nvis" : 3,
 DECLARED THE
                       "nhid" : 4,
  ELEMENTS OF
                       "irange" : 0.05,
                       "corruptor": !obj:pylearn2.corruption.BinomialCorruptor {
  THE SYSTEM.
                         "corruption level": 0.5,
                       "act enc": "tanh",
                       "act dec": null, # Linear activation on the decoder side.
  MUCH LIKE THE
                     "algorithm": !obj:pylearn2.training algorithms.sgd.SGD {
ORIGINAL TORCH. IT
                       "learning rate" : 1e-3,
  HAD NOTIONS OF
                       "batch size" : 5,
                       "monitoring dataset" : *dataset,
DATASET, MODEL, AND
                       "cost" : !obj:pylearn2.costs.autoencoder.MeanSquaredReconstructionError {},
                       "termination criterion" : !obj:pylearn2.termination criteria.EpochCounter {
    OPTIMIZER
                         "max epochs": 1,
   (ALGORITHM).
                     "save path": "./garbage.pkl"
```

```
import keras
                            from keras.models import Sequential
                            from keras.layers import Dense, Dropout, Activation
                            from keras.optimizers import SGD
                            # Generate dummy data
KERAS WAS ORIGINALLY A
                            import numpy as np
                            x train = np.random.random((1000, 20))
 WRAPPER FOR THEANO.
                            y train = keras.utils.to categorical(
                                np.random.randint(10, size=(1000, 1)), num classes=10)
                            x test = np.random.random((100, 20))
                            y test = keras.utils.to categorical(
                                np.random.randint(10, size=(100, 1)), num classes=10)
                            model = Sequential()
                            # Dense(64) is a fully-connected layer with 64 hidden units. In the
                            # first layer, you must specify the expected input data shape: here,
                            # 20-dimensional vectors.
                            model.add(Dense(64, activation='relu', input dim=20))
                            model.add(Dropout(0.5))
                            model.add(Dense(64, activation='relu'))
                            model.add(Dropout(0.5))
                            model.add(Dense(10, activation='softmax'))
                            sqd = SGD(lr=0.01, decay=1e-6, momentum=0.9, nesterov=True)
                            model.compile(
                                loss='categorical crossentropy', optimizer=sqd,
                            metrics=['accuracy'])
                            model.fit(x train, y train, epochs=20, batch size=128)
                            score = model.evaluate(x test, y test, batch size=128)
```

IT EMULATED TORCH7. **NOTICE SIMILARITIES SUCH AS SEQUENTIAL AND** MODEL.ADD.

The Keras functional API does away with containers and connects layers to their successors in the computational graph by passing the predecessor as an argument.

This replaces model.add with Python's \_\_call\_\_ method – effectively associating predecessors and successors with a pseudo-closure.

How might this be more flexible than a sequential container?

```
IN THE CONTAINER API, THIS WOULD BE
from keras.layers import Input, Dense
                                                                MODEL.ADD.
from keras.models import Model
# This returns a tensor.
inputs = Input(shape=(784,))
# A layer instance is callable on a tensor, and returns a tensor.
x = Dense(64, activation='relu') (inputs)'
x = Dense(64, activation='relu')(x)
predictions = Dense(10, activation='softmax')(x)
# This creates a model that includes the Input layer and three Dense
# layers.
model = Model(inputs=inputs, outputs=predictions)
model.compile(
    optimizer='rmsprop',
    loss='categorical crossentropy',
    metrics=['accuracy'])
model.fit(data, labels)
```